# Best Approximation of Lebesgue–Bochner Summable Functions

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In this paper the approximation properties of the space of functions with values in a Banach space which are summable in the sense of Bochner [1] are studied. We obtain some theorems on the characterization and unicity of best approximations related to those given by Cheney and Wulbert [5], Kripke and Rivlin [10], Pták [11], and Singer [12] for real-valued summable functions. In Section 4 we apply our results to an approximation problem similar to that investigated by Carroll and McLaughlin [4].

# 1. DEFINITIONS

Let I be the interval [0, 1],  $\mu$  the Lebesgue measure on I, and X a real Banach space with the norm  $|\cdot|$ . The class of all summable functions x(t) on I into X (for the definition of measurability and summability see [1]) provided with the norm

$$||x|| = \int_{I} |x(t)| dt$$

is a Banach space and will be denoted by L(X). Following Bochner and Taylor [3] we denote further by  $V^{\infty}(X)$  the class of all functions x(t) on Iinto X such that x(0) = 0 and such that there is a constant  $A \ge 0$  with the property  $|x(t+h) - x(t)| \le A |h|$ , whenever t and t+h belong to I. Denoting by N(x) the least such constant and defining the norm on  $V^{\infty}(X)$ by ||x|| = N(x),  $V^{\infty}(X)$  is a Banach space. The space of all continuous functions x(t) on I into X provided with the norm  $||x|| = \sup_{I} |x(t)|$  will be denoted by C(X). Let  $X^*$  be the conjugate space of X. For  $x \in L(X)$  and  $u \in V^{\infty}(X^*)$  let the integral

$$\int_{I} du(t) x(t)$$

be defined in the same way as in [3].

The following theorem gives the general form of linear bounded functionals on L(X).

THEOREM 1.1 (Bochner and Taylor [3]). For every  $f \in L^*(X)$  there is a  $u \in V^{\infty}(X^*)$  such that ||u|| = ||f|| and

$$f(x) = \int_{I} du(t) x(t) \tag{1.1}$$

for every  $x \in L(X)$ . Conversely, for every  $u \in V^{\infty}(X^*)$ , (1.1) defines a linear bounded functional f on L(X) with ||f|| = ||u||.

Let X be a normed linear space, E a subspace of X. For  $x \in X$  we denote by  $P_E(x)$  the set of all best approximations of x in E, i.e.,  $P_E(x) = \{e_0 \in E; \|x - e_0\| = \inf_{e \in E} \|x - e\|\}$ . E is said to be a U-space if for every  $x \in X$  the set  $P_E(x)$  contains at most one element of E. We further denote  $E^0 = \{x \in X; 0 \in P_E(x)\}$  and for a function x on I to X,  $R(x) = \{t; x(t) \neq 0\}$  and  $Z(x) = \{t; x(t) = 0\}$ . R and N will denote the set of all real numbers and the set of all positive integers, respectively.

## 2. MAXIMAL FUNCTIONALS ON L(X)

In the main theorem of this section we give characterizations in terms of "differentiability" of those functionals u on L(X) which are maximal, i.e., for which there is a  $x \in L(X)$  with  $ux = ||u|| \cdot ||x||$ . In the particular case that every function u on I to X which has bounded variation possesses the strong derivative a.e. in I, this theorem is a consequence of Theorem 2.2 [3]. There are, however, as shown in [2], a Banach space X and a function  $u \in V^{\infty}(X)$  such that u is not differentiable at any point in I.

We denote

$$u'(t) x(t) = \lim_{h \to 0} \frac{u(t+h) - u(t)}{h} x(t)$$

for  $u \in V^{\infty}(X^*)$ ,  $x \in L(X)$ , and every  $t \in I$  for which the limit exists.

LEMMA 2.1. Let  $Q \subseteq I$  be a closed set, X a Banach space,  $x: Q \to X$  a continuous function,  $u \in V^{\infty}(X^*)$ , ||u|| = 1. Let

$$\int_{Q} du(t) x(t) = \int_{Q} |x(t)| dt.$$
 (2.1)

Then we have

$$u'(t) x(t) = |x(t)|$$
 a.e. in Q.

*Proof.* Since ||u|| = 1, (2.1) implies

$$\int_{A} du(t) x(t) = \int_{A} |x(t)| dt$$
 (2.2)

for every measurable subset A of Q. The map x being continuous and bounded by a constant  $M \ge 1$ , it may be extended to a continuous map on the whole interval I bounded by the same constant M ([6, Theorem IX, 6.1]). This extension will be denoted by x again. For  $t \in Q$ ,  $h \ne 0$ ,  $z: Q \rightarrow X$  let us denote

$$D(t, h, z) = ((u(t+h) - u(t))/h) z(t).$$

The function  $\liminf_{h\to 0} D(t, h, x)$  is measurable (this fact may be proved in a way similar to that used to prove the measurability of the lower derivative of a real function). Since ||u|| = 1, we have for every  $t \in Q$ 

$$\limsup_{h\to 0} D(t, h, x) \leqslant |x(t)|.$$

We denote

$$G = \{t \in Q; \liminf_{h \to 0} D(t, h, x) < |x(t)|\},\$$
  
$$G_n = \{t \in Q; \liminf_{h \to 0} D(t, h, x) < |x(t)| - 1/n\}, \quad n \in \mathbb{N}.$$

Obviously  $G = \bigcup_{n=1}^{\infty} G_n$  and the proof of the lemma will be completed by showing that for every  $n \in \mathbb{N}$ ,  $\mu(G_n) = 0$ . Assume the converse. Then there is a  $n_0 \in \mathbb{N}$  such that for  $G_0 = G_{n_0}$  we have  $\mu(G_0) = a > 0$ .

Let  $\epsilon$  be an arbitrary real number,  $0 < \epsilon < a/2$ . Then there exist an open set  $H, G_0 \subset H$ , a closed set  $F, F \subset G_0$  and a continuous real function  $f: I \to I$  with f(t) = 1 for every  $t \in F$ , f(t) = 0 for every  $t \in I \setminus H$  such that

$$\mu(H \setminus G_0) < \epsilon/4M, \qquad \mu(G_0 \setminus F) < \epsilon/4M,$$
(2.3)

$$\left|\int_{G_0} |x(t)| \, dt - \int_I |y(t)| \, dt \right| < \epsilon, \tag{2.4}$$

and

$$\left|\int_{G_0} du(t) x(t) - \int_I du(t) y(t)\right| < \epsilon, \qquad (2.5)$$

where  $y = f \cdot x$ . Since y is a continuous function, there is a  $\delta > 0$  such that for an arbitrary partition P:  $t_0, ..., t_n$  of I and arbitrary points  $\tau_i \in [t_{i-1}, t_i]$ ,  $i = 1, ..., n, |P| = \max_i |t_i - t_{i-1}| < \delta$  implies

$$\left|\int_{I} du(t) y(t) - S(P)\right| < \epsilon, \qquad (2.6)$$

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where  $S(P) = \sum_{j=1}^{n} (u(t_j) - u(t_{j-1})) y(\tau_j)$  and

$$\left|\int_{I} |y(t)| dt - \sum_{j=1}^{n} |y(\tau_{j})| (t_{j} - t_{j-1})\right| < \epsilon.$$
(2.7)

Since  $F \subseteq G_0$  , there exists for every  $t \in F$  a sequence  $\{h_k(t)\}_{k \in \mathbb{N}}$  with the properties

$$0 < |h_k(t)| < \delta$$
 for every  $k \in \mathbb{N}$  and every  $t \in F$ ,  
 $\lim_{k \to \infty} h_k(t) = 0$  for every  $t \in F$ ,

and

$$D(t, h_k(t), y) < |y(t)| - 1/n_0$$
(2.8)

for every  $t \in F$  and  $k \in \mathbb{N}$ . The class of all intervals  $[t, t + h_k(t)]$  (or  $[t + h_k(t), t]$  if  $h_k(t) < 0$ ),  $t \in F$ , covers the set F in the sense of Vitali [7]. Hence it has a finite disjoint subclass  $I(t_i)$ , i = 1, ..., m, such that

$$\mu\left(F \setminus \bigcup_{i=1}^{m} I(t_i)\right) < \epsilon/2M.$$
(2.9)

Let  $P_0$  be a partition of *I* consisting of all boundary points  $t_i$ ,  $t_i + h_i$  of the intervals  $I(t_i)$ , i = 1,...,m. Let  $P_1 : s_0,...,s_p$  be a refinement of  $P_0$  such that none of the points  $s_j$ , j = 0,...,p, is contained in any open interval Int  $I(t_i)$ , i = 1,...,m.

For every index j = 1,..., p exactly one of the following conditions can be satisfied:

(i)  $[s_{j-1}, s_j] = I(t_i)$  for some i = 1, ..., m. In this case we put  $\tau_j = t_i$ .

(ii)  $[s_{j-1}, s_j] \cap (I \setminus H) \neq \emptyset$  and (i) does not hold. In this case we choose an arbitrary  $\tau_j \in [s_{j-1}, s_j] \cap (I \setminus H)$ .

(iii)  $[s_{j-1}, s_j] \cap (I \setminus H) = \emptyset$  and (i) does not hold. In this case we choose an arbitrary  $\tau_j \in [s_{j-1}, s_j]$ .

Denoting by B the set of all indices j which satisfy condition (iii), we have by (2.3) and (2.8)

$$egin{aligned} &\mu\left(igcup_{j\in B}\left[s_{j-1}\,,\,s_{j}
ight]
ight)\leqslant\mu\left(Higcap_{i=1}^{m}I(t_{i})
ight)\ &\leqslant\mu(Hackslash F)+\mu\left(Figcap_{i=1}^{m}I(t_{i})
ight)<\epsilon/M. \end{aligned}$$

Hence, we have by (2.4)–(2.9)

$$\begin{split} \int_{G_0} du(t) \, x(t) &\leq \int_I du(t) \, y(t) + \epsilon < \sum_{j=1}^p \left( u(s_j) - u(s_{j-1}) \right) \, y(\tau_j) + 2\epsilon \\ &\leq \sum_{i=1}^m D(t_i \, , \, h_i \, , \, y) \mid h_i \mid + \sum_{j \in B} \left( u(s_j) - u(s_{j-1}) \right) \, y(\tau_j) + 2\epsilon \\ &\leq \sum_{i=1}^m \left( \mid y(t_i) \mid - 1/n_0 \right) \mid h_i \mid + M \cdot \mu \left( \bigcup_{j \in B} \left[ s_{j-1} \, , \, s_j \right] \right) + 2\epsilon \\ &\leq \sum_{i=1}^m \mid y(t_i) \mid \mid h_i \mid - \sum_{i=1}^m \left( 1/n_0 \right) \mid h_i \mid + 3\epsilon \\ &\leq \sum_{j=1}^p \mid y(\tau_j) \mid \left( s_j - s_{j-1} \right) - \sum_{i=1}^m \left( 1/n_0 \right) \mid h_i \mid + 3\epsilon. \end{split}$$

Since by (2.3) and (2.9),  $\sum_{i=1}^{m} |h_i| = \mu(\bigcup_{i=1}^{m} I(t_i)) > a/2$ , we have by (2.4) and (2.7) for every  $\epsilon$ ,  $0 < \epsilon < a/2$ ,

$$\int_{G_0} du(t) \, x(t) < \int_{G_0} |x(t)| \, dt - a/2n_0 + 5\epsilon.$$

This, however, for  $\epsilon < a/10n_0$ , contradicts (2.2).

LEMMA 2.2. For  $u \in V^{\infty}(X^*)$ ,  $x \in L(X)$ , let u'(t) x(t) exist a.e. in I. Then

$$\int_{I} u'(t) x(t) dt = \int_{I} du(t) x(t).$$
(2.10)

Proof. Since

$$|u'(t) x(t)| = \lim_{h \to 0} 1/|h| |(u(t+h) - u(t)) x(t)|$$
  

$$\leq ||u|| |x(t)| \text{ a.e. in } I, \qquad (2.11)$$

u'(t) x(t) is summable. Let  $\epsilon > 0$  be given. Then there is a  $\delta > 0$  such that for every measurable set  $G \subset I, \mu(G) < \delta$  implies

$$\int_{G} |x(t)| dt < \epsilon/||u||.$$
(2.12)

By Lusin's theorem there is a  $y \in C(X)$  such that  $\mu(R(x - y)) < \delta/3$  and

$$\int_{I} |x(t) - y(t)| \, dt < \epsilon / || \, u \, ||, \qquad (2.13)$$

and a  $v \in C(\mathbb{R})$  such that  $\mu(R(v - u'x)) < \delta/3$  and

$$\int_{I} |u'(t) x(t) - v(t)| dt < \epsilon.$$
(2.14)

We have v(t) = u'(t) x(t) for every  $t \in N = (I \setminus (R(x - y) \cup R(v - u'x))) \setminus M$ ,  $\mu(M) = 0$ . We choose an  $\eta$ ,  $0 < \eta < \delta$ , such that for every partition P,  $|P| < \eta$  implies

$$\left|S(P) - \int_{I} du(t) y(t)\right| < \epsilon$$
(2.15)

and  $|t_1 - t_2| < \eta$  implies

$$|v(t_1) - v(t_2)| < \epsilon. \tag{2.16}$$

For every  $t \in N$  there exists a sequence  $h_n(t) \to 0$  such that for every  $n \in \mathbb{N}$ ,  $0 < h_n(t) < \eta$  and

$$|D(t, h_n(t), x) - u'(t) x(t)| < \epsilon.$$
(2.17)

Since the class of all intervals  $[t, t + h_n(t)]$ ,  $t \in N$ ,  $n \in \mathbb{N}$ , covers the set N in the sense of Vitali, there is a  $k \in \mathbb{N}$  and a disjoint subclass  $[t_j, t_j + h_j]$ , j = 1, ..., k, such that we have

$$\mu\left(N\Big\backslash\bigcup_{j=1}^{k}\left[t_{j},t_{j}+h_{j}\right]\right)<\delta/3.$$
(2.18)

Let  $P: s_0, ..., s_n$  be a refinement of the partition  $P_1: t_1, ..., t_n + h_n$  such that  $|P| < \eta$ , there is no index i = 0, ..., n such that  $s_i \in \text{Int}[t_i, t_j + h_j]$  for some j = 1, ..., k and

$$\left|\int_{I\setminus \bigcup_{j=1}^{k}[t_{j},t_{j}+h_{j}]} du(t) y(t) - \sum_{\substack{i=0\\i\notin A}}^{n} (u(s_{i+1}) - u(s_{i})) y(s_{i})\right| < \epsilon, \quad (2.19)$$

where A is the set of all indices i such that there is a j = 1,..., k with  $s_i = t_j$ . Let us put

$$w(t) = \sum_{i=0}^{n} \frac{u(s_{i+1}) - u(s_i)}{s_{i+1} - s_i} y(s_i) \chi_{[s_i, s_{i+1}]}(t),$$

where  $\chi$  is the characteristic function. By (2.15), we have

$$\left|\int_{I}w(t)\,dt-\int_{I}du(t)\,y(t)\right|<\epsilon.$$

Further, by (2.11)-(2.14), (2.16), (2.17), (2.19), we have

$$\begin{split} \left| \int_{I} w(t) \, dt - \int_{I} v(t) \, dt \right| \\ &\leqslant \sum_{j=1}^{k} \int_{[t_{j}, t_{j} + h_{j}]} |D(t_{j}, h_{j}, x) - v(t)| \, dt \\ &+ \int_{I} \left| \sum_{\substack{i=0 \\ i \notin A}}^{n} \left( \frac{u(s_{i+1}) - u(s_{i})}{s_{i+1} - s_{i}} y(s_{i}) - v(t) \right) \chi_{[s_{i}, s_{i+1}]}(t) \right| \, dt \\ &\leqslant \sum_{j=1}^{k} \int_{[t_{j}, t_{j} + h_{j}]} |D(t_{j}, h_{j}, x) - u'(t_{j}) x(t_{j})| \, dt \\ &+ \sum_{j=1}^{k} \int_{[t_{j}, t_{j} + h_{j}]} |u'(t_{j}) x(t_{j}) - v(t)| \, dt \\ &+ \left| \int_{I} \sum_{\substack{i=0 \\ i \notin A}}^{n} \frac{u(s_{i+1}) - u(s_{i})}{s_{i+1} - s_{i}} y(s_{i}) \chi_{[s_{i}, s_{i+1}]}(t) \, dt \right| + \left| \int_{\bigcup_{i=0, i \notin A}}^{n} [s_{i}, s_{i+1}] v(t) \, dt \right| \\ &< 2\epsilon + \left| \sum_{\substack{i=0 \\ i \notin A}}^{n} (u(s_{i+1}) - u(s_{i})) y(s_{i}) \right| + 2\epsilon < 7\epsilon. \end{split}$$

Further, by (2.13), we have

$$\left|\int_{I} du(t) x(t) - \int_{I} du(t) y(t)\right| < \epsilon.$$

Hence

$$\begin{aligned} \left| \int_{I} du(t) x(t) - \int_{I} u'(t) x(t) dt \right| \\ &\leq \left| \int_{I} du(t) x(t) - \int_{I} du(t) y(t) \right| \\ &+ \left| \int_{I} du(t) y(t) - \int_{I} w(t) dt \right| + \left| \int_{I} w(t) dt - \int_{I} v(t) dt \right| \\ &+ \left| \int_{I} v(t) dt - \int_{I} u'(t) x(t) dt \right| < 10\epsilon. \end{aligned}$$

THEOREM 2.3. Let  $x \in L(X)$ ,  $u \in V^{\infty}(X^*)$ , ||u|| = 1. Then we have

$$\int_{I} du(t) x(t) = \int_{I} |x(t)| dt$$
 (2.20)

if and only if

$$u'(t) x(t) = |x(t)|$$
 a.e. in I. (2.21)

*Proof.* If (2.21) holds, then we have (2.20) by Lemma 2.2.

Conversely, let (2.20) be satisfied. Then by Lusin's theorem, for every  $n \in \mathbb{N}$  there is an open set  $R_n$  such that  $\mu(R_n) < 1/n$  and such that x is continuous on  $I \setminus R_n$ . Since for every  $n \in \mathbb{N}$ , (2.20) implies

$$\int_{I\setminus R_n} du(t) x(t) = \int_{I\setminus R_n} |x(t)| dt,$$

we have (2.21) by Lemma 2.1.

Remark 2.4. Let  $u \in V^{\infty}(X^*)$ ,  $x \in L(X)$ ,  $y(t) = \alpha(t) \cdot x(t)$  a.e. in *I*, where  $\alpha$  is a real function on *I*. Let u'(t)x(t) exist a.e. in *I*. Then we obviously have  $u'(t)y(t) = \alpha(t) \cdot u'(t)x(t)$  a.e. in *I*.

## 3. Best Approximation in L(X)

The following theorem characterizes elements of best approximation in L(X). The equivalence (i)  $\Leftrightarrow$  (iii) is a generalization of a well-known theorem for real-valued summable functions given by James [8] and Kripke and Rivlin [10]. Our proof of the implication (iii)  $\Rightarrow$  (i) is a modification of Singer's proof [12].

THEOREM 3.1. Let E be a linear subspace of L(X),  $x \in L(X) \setminus \overline{E}$ ,  $e_0 \in E$ . Then the following conditions are equivalent:

- (i)  $e_0 \in P_E(x)$
- (ii) There exists a  $u \in V^{\infty}(X^*)$ , ||u|| = 1 such that we have

$$u'(t)(x(t) - e_0(t)) = |x(t) - e_0(t)| \quad a.e. \text{ in } I$$
(3.1)

and

$$\int_{I} du(t) e(t) = 0 \quad \text{for every } e \in E.$$
(3.2)

(iii) There exists a  $u \in V^{\infty}(X^*)$ , ||u|| = 1, such that we have (3.1) and

$$\left|\int_{R(x-e_0)} du(t) e(t)\right| \leqslant \int_{Z(x-e_0)} |e(t)| dt \quad \text{for all } e \in E.$$
(3.3)

*Proof.* (i) implies (ii): This is an immediate consequence of Singer's Theorem 1.1 [12], and Theorems 1.1 and 2.3 above.

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(ii) implies (iii): For every  $e \in E$  we have by (3.2)

$$\left|\int_{R(x-e_0)} du(t) e(t)\right| \leqslant \left|\int_{Z(x-e_0)} du(t) e(t)\right| \leqslant \int_{Z(x-e_0)} |e(t)| dt.$$

(iii) implies (i): Let  $e \in E$ . It follows from the Hahn-Banach theorem that there exists a  $u_1 \in V^{\infty}(X^*)$ ,  $||u_1|| = 1$ , such that we have

$$\int_{I} du_{1}(t)(e_{0}(t) - e(t)) = \int_{I} |e_{0}(t) - e(t)| dt$$

Hence

$$\int_{Z(x-e_0)} du_1(e_0-e) = \int_{Z(x-e_0)} |e_0-e| dt.$$

Defining

we obtain  $||u_2|| \leq 1$  and

$$\int_{R(x-e_0)} du(e_0-e) + \int_{Z(x-e_0)} du_2(e_0-e) = 0.$$

Hence

$$\|x - e_0\| = \int_{R(x-e_0)} du(x - e_0) = \int_{R(x-e_0)} du(x - e_0) + \int_{R(x-e_0)} du(e_0 - e) + \int_{Z(x-e_0)} du_2(e_0 - e) + \int_{Z(x-e_0)} du_2(x - e_0) = \int_{R(x-e_0)} du(x - e) + \int_{Z(x-e_0)} du_2(x - e) \\ \leqslant \int_{R(x-e_0)} |x - e| dt + \int_{Z(x-e_0)} |x - e| dt = ||x - e||.$$

The next theorem gives equivalent conditions for a linear subspace E of L(X) to be a U-space. Similar theorems for real-valued summable functions have been proved by Cheney and Wulbert [5, Theorem 21] and Singer [12, Theorem 3.4].

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LEMMA 3.2. Let X be a strict convex Banach space and let  $x \in L(X)$  have two best approximations  $e_1, e_2 \in E, e_1 \neq e_2$ . Then we have

$$Z(x - e_0) \subseteq Z(e_1 - e_2), \tag{3.4}$$

where  $e_0 = e_1/2 + e_2/2$  and there exists a real nonnegative function  $\alpha$  such that

$$x(t) - e_1(t) = \alpha(t) \cdot (x(t) - e_2(t))$$
 a.e. in  $R(x - e_2)$ . (3.5)

*Proof.* Since  $e_1$ ,  $e_2$ ,  $e_0 \in P_E(x)$ , we have

$$\int_{I} (|x - e_1| + |x - e_2| - 2 |x - e_0|) dt = 0$$

The integrand being nonnegative, we must have

$$|x(t) - e_1(t)| + |x(t) - e_2(t)| = 2 |x(t) - e_0(t)|$$
 a.e. in *I*,

which implies (3.4) (this argument is due to Cheney and Wulbert [5]). Since X is strict convex, there exists a real nonnegative function  $\alpha$  such that (3.5) holds.

THEOREM 3.3. Let X be a strict convex Banach space, E a linear subspace of L(X). Then the following conditions are equivalent:

(i) E is not a U-space.

(ii) There exist an  $x \in E^0$ , an  $e_0 \in E \setminus \{0\}$ , and a real function  $\alpha$ ,  $|\alpha| \leq 1$ , such that

$$e_0(t) = \alpha(t) \cdot x(t) \qquad a.e. \text{ in } I. \tag{3.6}$$

(iii) There exist a  $u \in V^{\infty}(X^*)$ , ||u|| = 1, and an  $e_0 \in E \setminus \{0\}$  such that

$$\int_{I} du(t) e(t) = 0 \quad \text{for every } e \in E$$
(3.7)

and

$$|u'(t) e_0(t)| = |e_0(t)|$$
 a.e. in I. (3.8)

*Proof.* (i) implies (ii): If E is not a U-space then there exist an  $x \in E^0$  and an  $e_0 \in E \setminus \{0\}$  such that  $e_0$ ,  $-e_0 \in P_E(x)$  (see e.g., [11, remark following 1.3]). By Lemma 3.2 there exist real nonnegative functions  $\alpha_1$  and  $\alpha_2$  such that we have

$$\begin{aligned} \mathbf{x}(t) - \mathbf{e}_0(t) &= \alpha_1(t) \cdot \mathbf{x}(t) & \text{a.e. in } R(\mathbf{x}), \\ \mathbf{x}(t) + \mathbf{e}_0(t) &= \alpha_2(t) \cdot \mathbf{x}(t) & \text{a.e. in } R(\mathbf{x}). \end{aligned}$$

Since  $\alpha_1$  and  $\alpha_2$  are nonnegative, we must have

$$|\alpha_2(t)-1| \leq 1$$
 a.e. in  $R(x)$ .

On the other hand, we have by Lemma 3.2,  $Z(x) \subset Z(e_0)$ . Thus the function

$$\alpha(t) = \alpha_2(t) - 1 \quad \text{for } t \in R(x)$$
$$= 0 \quad \text{for } t \in Z(x)$$

has the required properties.

(ii) implies (iii): If (ii) is satisfied then by Theorem 3.1 there is a  $u \in V^{\infty}(X^*)$ , ||u|| = 1, such that we have (3.7) and such that u'(t) x(t) = |x(t)| a.e. in *I*. Hence by Remark 2.4 we obtain

$$|u'(t) e_0(t)| = |u'(t)(\alpha(t) \cdot x(t))| = |\alpha(t)| \cdot |x(t)| = |e_0(t)|$$
 a.e. in *I*.

(iii) implies (i): Let us define

$$y(t) = 2e_0(t) \cdot \operatorname{sign} u'(t) e_0(t) \quad \text{for} \quad t \in I.$$

Then, by Remark 2.4, we obviously have u'(t) y(t) = |y(t)| a.e. in *I* and  $u'(t)(y(t) - e_0(t)) = |y(t) - e_0(t)|$  a.e. in *I*. Thus by Theorem 3.1, 0 and  $e_0$  are best approximations of y.

*Remark* 3.4. The condition "There exist an  $x \in E^0$  and an  $e \in E \setminus \{0\}$  such that  $Z(e) \supset Z(x)$ ," which in the case of real-valued functions is necessary and sufficient for E not to be a *U*-space [5], is not sufficient in the case of vector-valued functions.

EXAMPLE. Let  $X = \mathbb{R}^2$  with the Euclidean norm  $|\cdot|$ . Then every  $x \in L(X)$  has the form x = (y, z), where  $y, z \in L_1$ ,  $L_1$  the space of all Lebesgue-summable real-valued functions. Let

$$E = \{e; e = (f, 0), f \in L_1\}.$$

Then we have for  $x \in L(X)$ , x = (y, z), and  $e \in E$ , e = (f, 0),

$$||x - e|| = \int_{I} |x - e| dt = \int_{I} (|y - f|^{2} + |z|^{2})^{1/2} dt.$$

Thus (y, 0) is the only best approximation of x in E and E is a U-space. On the other hand, for every  $x = (0, z) \in E^0$  there exists an  $e \in E \setminus \{0\}$ , namely e = (z, 0), such that  $Z(e) \supset Z(x)$ .

*Remark* 3.5. If X is not a strict convex Banach space, condition (ii) of Theorem 3.3 is not necessary for E not to be a U-space.

EXAMPLE. Let  $X = \mathbb{R}^2$  with the norm  $|x| = |(x_1, x_2)| = \text{Max}(|x_1|, |x_2|)$ , E the same subspace of L(X) as in Remark 3.4. Since for every  $x \in L(X)$  of the form x = (0, y) and  $e \in E$ , e = (f, 0),

$$||x - e|| = \int_{I} \operatorname{Max}(|f|, |y|) dt,$$

every  $e = (f, 0) \in E$  such that  $|f| \leq |y|$  is a best approximation of x. On the other hand, if there exist an  $x \in E^0$ , x = (y, z), an  $e \in E$ , e = (f, 0), and a real function  $\alpha$  such that  $e = \alpha \cdot x$  a.e. in *I*, we must have  $|y| \leq |z|$ a.e. in *I* which implies that e = 0 a.e. in Z(z) and  $\alpha = 0$  a.e. in R(z). Thus e = 0 is the only element of *E* with the property  $e = \alpha \cdot x$ .

## 4. AN APPLICATION TO SIMULTANEOUS APPROXIMATION

Let  $m, n \in \mathbb{N}$ ,  $f_1, ..., f_m \in L_1$ , and  $P_n$  be the space of all polynomials of degree less than or equal to n. Carroll and McLaughlin [4] considered the problem of finding a  $p_0 \in P_n$  such that

$$\sum_{i=1}^{m} \int_{I} |f_{i} - p_{0}| dt = \inf_{p \in P_{n}} \sum_{i=1}^{m} \int_{I} |f_{i} - p| dt.$$
(4.1)

As remarked in [4], if m is even, the best approximation in this sense need not be unique.

Let  $X = \mathbb{R}^m$  with the norm  $|x| = |(x_1, ..., x_m)| = \sum_{i=1}^m |x_i|$  and let E be the space of all  $e = (e_1, ..., e_m) \in L(X)$  such that there exists a  $p \in P_n$  with  $e_i = p$  for every i = 1, ..., m. Obviously, problem (4.1) is equivalent to the problem of finding for  $x \in L(X)$  a best approximation in E. We show that there is a norm in X, namely every strict convex norm, such that the best approximation is always unique. We formulate this more generally.

Let A be an arbitrary set of indices,  $X = \mathbb{R}^A$  a strict convex Banach space, Q a subspace of  $L_1$  such that  $\mu(Z(q)) = 0$  for every  $q \in Q \setminus \{0\}$ . For every  $q \in Q$ let L(X) contain the element  $e = \{e_a\}, e_a = q$ , for every  $a \in A$ . Let E be the subspace of all such elements. An element  $x = \{x_a\} \in L(X)$  will be said to have the property (P) if there are indices a and b in A such that  $x_a \neq x_b$  in a set of positive measure.

THEOREM 4.1. For every  $x \in L(X)$  with the property (P) the set  $P_E(x)$  contains at most one element.

*Proof.* If there is an  $x \in L\{X\}$  such that e and  $-e \in E \setminus \{0\}$  are best approximations of x, then by the proof of Theorem 3.3 there is a real function  $\alpha$ 

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such that  $e = \alpha \cdot x$  a.e. in *I*. Since  $e(t) \neq 0$  a.e. in *I*, we have  $\alpha(t) \neq 0$  a.e. in *I*. Thus  $x(t) = 1/\alpha(t) \cdot e(t)$  a.e. in *I*, which implies that x cannot have the property (*P*).

The following corollaries are immediate consequences of Theorem 4.1.

COROLLARY 4.2. Let *m* be an integer,  $m \ge 2$ . Then for every  $x = (x_1, ..., x_m), x_i \in L_1, i = 1, ..., m$ , satisfying the condition (P) there is at most one  $q_0 \in Q$  such that

$$\int_{I} \left( \sum_{i=1}^{m} |x_{i}(t) - q_{0}(t)|^{2} \right)^{1/2} dt = \inf_{q \in Q} \int_{I} \left( \sum_{i=1}^{m} |x_{i}(t) - q(t)|^{2} \right)^{1/2} dt.$$

COROLLARY 4.3. For every  $x = \{x_i\}_{i=1}^{\infty}$ ,  $x_i \in L_1$ ,  $i \in \mathbb{N}$ , satisfying the condition (P) and such that  $\sup_{i \in \mathbb{N}} \int_I |x_i(t)| dt < +\infty$  there exists at most one  $q_0 \in Q$  such that

$$\int_{I} \left( \sum_{i=1}^{\infty} \frac{1}{2^{i}} |x_{i}(t) - q_{0}(t)|^{2} \right)^{1/2} dt = \inf_{q \in Q} \int_{I} \left( \sum_{i=1}^{\infty} \frac{1}{2^{i}} |x_{i}(t) - q(t)|^{2} \right)^{1/2} dt.$$

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